STATS305C: Applied Statistics III

Lecture 16: Poisson processes

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Outline

- Defining properties of a Poisson process
- Four ways to sample a Poisson process
- Beyond Poisson: Doubly stochastic processes

Defining properties of a Poisson process

- ▶ Poisson processes are **stochastic processes** that generate **random sets of points** $\{x_n\}_{n=1}^N \subset \mathcal{X}$.
- Poisson processes are governed by an **intensity** function, $\lambda(\mathbf{x}) : \mathscr{X} \to \mathbb{R}_+$.
- Property #1: The number of points in any interval is a Poisson random variable,

$$N(\mathscr{A}) \sim \operatorname{Po}\left(\int_{\mathscr{A}} \lambda(\boldsymbol{x}) \, \mathrm{d}\boldsymbol{x}\right)$$

Property #2: Disjoint intervals are independent,

$$N(\mathscr{A}) \perp N(\mathscr{B}) \iff \mathscr{A} \cap \mathscr{B} = \emptyset \qquad (2)$$



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Example applications of Poisson processes

- Modeling neural firing rates
- Locations of trees in a forest
- Locations of stars in astronomical surveys
- Arrival times of customers in a queue (or HTTP requests to a server)
- Locations of bombs in London during World War II
- Times of photon detections on a light sensor
- Others?

Four ways to sample a Poisson process

- **1.** The top-down approach
- 2. The interval approach
- **3.** The time-rescaling approach
- **4.** The thinning approach

Top-down sampling of a Poisson process

Given $\lambda(\mathbf{x})$ (and a domain \mathscr{X}):

1. Sample the total number of points



2. Sample the locations of the points

$$\mathbf{x}_n \stackrel{\text{iid}}{\sim} \frac{\lambda(\mathbf{x})}{\int_{\mathscr{X}} \lambda(\mathbf{x}') \, \mathrm{d}\mathbf{x}'}$$
 } point

for n = 1, ..., N.

Question: what assumptions are necessary for this procedure to be tractable?

1. computer integral; 2. Sample iid.

(4)

Deriving the Poisson process likelihood

Exercise: from the top-down sampling process, derive the Poisson process likelihood,

$$p(\{x_n\}_{n=1}^{N} \mid \lambda(x)) = p(N \mid \lambda) \prod_{n=1}^{N} p(x_n \mid \lambda) \cdot N!$$

$$= P_0(N \mid \int_{Y} \lambda(x) dx) \prod_{n=1}^{N} \frac{\lambda(x_n)}{\int_{Y} \lambda(x) dx} \cdot N!$$

$$= \frac{1}{N!} e^{-\int_{Y} \lambda(x) dx} \prod_{n=1}^{N} \frac{\lambda(x_n)}{\int_{Y} \lambda(x) dx} \cdot N!$$

$$= e^{-\int_{Y} \lambda(x) dx} \prod_{n=1}^{N} \lambda(x_n)$$

(5)

Intervals of a homogeneous Poisson process

• A Poisson process is **homogeneous** if its intensity is constant, $\lambda(\mathbf{x}) \equiv \lambda$.

Property #3: A homogeneous Poisson process on $[0, T] \subset \mathbb{R}$ (e.g. where points correspond to arrival times) has independent, exponentially distributed intervals,

$$\Delta_n = x_n - x_{n-1} \stackrel{\text{iid}}{\sim} \operatorname{Exp}(\lambda) \tag{6}$$

Property #4: A homogeneous Poisson process is memoryless — the amount of time until the next point arrives is independent of the time elapsed since the previous point arrived.

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Sampling a homogeneous Poisson process by simulating intervals

We can sample a homogeneous Poisson process on [0, T] by simulating intervals as follows:

- **1.** Initialize $X = \emptyset$ and $x_0 = 0$
- **2.** For *n* = 1, 2, . . .:
 - Sample $\Delta_n \sim \operatorname{Exp}(\lambda)$.
 - Set $x_n = x_{n-1} + \Delta_n$.
 - If $x_n > T$, break and return **X**,
 - ► Else, set $X \leftarrow X \cup \{x_n\}$.



Deriving the likelihood of a homogeneous Poisson process

Exercise: from the interval sampling process, derive the likelihood of a homogeneous Poisson process. Show that it is the same as what you derived from the top-down sampling process.

$$P(\{x_n\}_{n=1}^{\infty} | \lambda) = P(\{\lambda_n\}|\lambda)$$

$$= \begin{bmatrix} \prod_{n=1}^{\nu} Ex_{p}(\lambda_{n}|\lambda) \end{bmatrix} Pr(\lambda_{n+1} > T - \sum_{n=1}^{\nu} \lambda_{n})$$

$$= \prod_{n=1}^{\nu} \lambda e^{-\lambda_{n}} \int_{T - \sum_{n=1}^{\nu} \lambda_{n}}^{\infty} d\lambda$$

$$= \begin{bmatrix} \prod_{n=1}^{\nu} \lambda e^{-\lambda_{n}} \end{bmatrix} e^{-(T - \sum_{n=1}^{\nu} \lambda_{n})}$$

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$$T > = \int_{0}^{T} \lambda dx$$

$$T > = \int_{0}^{\tau} \lambda dx$$

- ▶ Now consider an **inhomogeneous** Poisson process on [0, *T*]; i.e. one with a non-constant intensity.
- Apply the change of variables,

$$\mathbf{x} \mapsto \int_{0}^{x} \lambda(t) \, \mathrm{d}t \triangleq \Lambda(x) \tag{7}$$

Note that this is an **invertible transformation** when $\lambda(x) > 0$.

Sample a homogeneous Poisson process with unit rate on $[0, \Lambda(T)]$ to get points $U = \{u_n\}_{n=1}^N$. Then set,

$$\boldsymbol{X} = \{\Lambda^{-1}(\boldsymbol{u}_n) : \boldsymbol{u}_n \in \boldsymbol{U}\}.$$
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Note: this is the analog of inverse-CDF sampling.



- Brown et al. [2002] used the time-rescaling sampling procedure to develop a goodness-of-fit test for inhomogeneous Poisson processes.
- Suppose you observe a set of points $\{x_n\}_{n=1}^N \subset [0, T]$ and you want to test whether they are well-modeled by an inhomogeneous Poisson process with rate $\lambda(x)$.

Let $\Delta_n = \Lambda(x_n) - \Lambda(x_{n-1})$ with $\Lambda(x_0) = 0$. If the model is a good fit, then $\Delta_n \stackrel{\text{iid}}{\sim} \text{Exp}(1)$.

- ▶ Perform a further transformation $z_n = 1 e^{-\Delta_n}$. Then $z_n \stackrel{\text{iid}}{\sim} \text{Unif}([0, 1])$.
- Now sort the z_n 's in increasing order into $(z_{(1)}, \ldots, z_{(N)})$, so $z_{(1)}$ is the smallest value.
- ► Intuitively, the points $\left(\frac{n-1/2}{N}, z_{(n)}\right)$ should like along a 45° line.

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(9)

- We can check for significant departures from the 45° line using a simple visual test.
- The order statistics $z_{(n)}$ are marginally beta distributed,

 $z_{(n)} \sim \operatorname{Beta}(n, N-n+1)$

The mean is $\frac{n}{N+1}$ and its mode is $\frac{n-1}{N-1}$.

Then, use the 2.5% and 97.5% quantiles of the beta distribution to obtain confidence intervals around the 45° line.



Figure: Figure 1 from Brown et al. [2002].

The Poisson Superposition Principle

- Property #5: The union (a.k.a. superposition) of independent Poisson processes is also a Poisson process.
- Suppose we have two independent Poisson processes on the same domain \mathscr{X} ,

$$\{\boldsymbol{x}_n\}_{n=1}^N \sim \operatorname{PP}(\lambda_1(\boldsymbol{x})) \tag{10}$$
$$\{\boldsymbol{x}_m'\}_{m=1}^M \sim \operatorname{PP}(\lambda_2(\boldsymbol{x})) \tag{11}$$

Then

$$\{\boldsymbol{x}_n\}_{n=1}^N \cup \{\boldsymbol{x}_m'\}_{m=1}^M \sim \operatorname{PP}(\lambda_1(\boldsymbol{x}) + \lambda_2(\boldsymbol{x}))$$
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Poisson thinning



- Suppose we have points $\{\mathbf{x}_n\}_{n=1}^N \sim \operatorname{PP}(\lambda(\mathbf{x}))$ where $\lambda(\mathbf{x}) = \lambda_1(\mathbf{x}) + \lambda_2(\mathbf{x})$. Sample independent binary variables

$$z_n \sim \operatorname{Bern}\left(\frac{\lambda_1(\boldsymbol{x}_n)}{\lambda_1(\boldsymbol{x}_n) + \lambda_2(\boldsymbol{x}_n)}\right).$$
 (13)

Then $\{\mathbf{x}_n : z_n = 1\} \sim \operatorname{PP}(\lambda_1(\mathbf{x}))$ and $\{\mathbf{x}_n : z_n = 0\} \sim \operatorname{PP}(\lambda_2(\mathbf{x}))$.

Sampling a Poisson process by thinning

Exercise: Use Poisson thinning to sample an inhomogeneous Poisson process with a bounded intensity, $\lambda(\mathbf{x}) \leq \lambda_{\max}$.

Question: What Monte Carlo sampling method is this akin to?



Outline

- Defining properties of a Poisson process
- Four ways to sample a Poisson process
- Beyond Poisson

What's not to love about Poisson processes?

• independence

- One way of introducing dependence is via an autoregressive model. Consider a point process on a time interval [0, T].
- Let $\lambda(t \mid \mathscr{H}_t)$ denote a **conditional intensity function** where \mathscr{H}_t is the **history** of points before time *t*.
- Frechnically, \mathscr{H}_t is a **filtration** in the language of stochastic processes.
- Allowing past points to influence the intensity function enables more complex, non-Poisson models.

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Hawkes processes

► Hawkes processes [Hawkes, 1971] are **self-exciting point processes**.

Their conditional intensity function is modeled as,

$$\lambda(t \mid \mathscr{H}_t) = \lambda_0 + \sum_{t_n \in \mathscr{H}_t} h(t - t_n), \qquad (14)$$

where $h : \mathbb{R}_+ \mapsto \mathbb{R}_+$ is a positive **impulse response** or **influence function**.

For example, the impulse responses could be modeled as exponential functions,

$$h(\Delta t) = \frac{w}{\tau} e^{-\frac{\Delta t}{\tau}} = w \cdot \operatorname{Exp}(\Delta t; \tau),$$
(15)

where $\tau \in \mathbb{R}_+$ is a time-constant governing the rate of decay and $w \in \mathbb{R}_+$ is a scaling parameter such that $\int_0^\infty h(\Delta t) d\Delta t = w$.

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Hawkes processes, in pictures



Maximum likelihood estimation for Hawkes processes I

- Suppose we observe a collection of time points $\{t_n\}_{n=1}^N \subset [0, T]$ and want to estimate the parameters $\theta = (\lambda_0, w)$ of a Hawkes process with an exponential impulse response function. (Consider τ to be fixed.)
- The Hawkes process log likelihood is just like that of a Poisson process,

$$\log p(\{t_n\}_{n=1}^N \mid \boldsymbol{\theta}) = -\int_0^T \lambda_{\boldsymbol{\theta}}(t \mid \mathscr{H}_t) \, \mathrm{d}t + \sum_{n=1}^N \log \lambda_{\boldsymbol{\theta}}(t_n \mid \mathscr{H}_t) \tag{16}$$

Maximum likelihood estimation for Hawkes processes II

Substituting in the form of the conditional intensity, we can simplify the log likelihood to,

$$\log p(\lbrace t_n \rbrace_{n=1}^N \mid \boldsymbol{\theta}) = -\int_0^T \left[\lambda_0 + w \sum_{t_n \in \mathscr{H}_t} \operatorname{Exp}(t - t_n; \tau) \, \mathrm{d}t \right] \\ + \sum_{n=1}^N \log \left(\lambda_0 + w \sum_{t_n \in \mathscr{H}_{t_n}} \operatorname{Exp}(t_n - t_m; \tau) \right) \quad (17)$$
$$\approx -\boldsymbol{\theta}^\top \boldsymbol{\phi}_0 + \sum_{n=1}^N \log \left(\boldsymbol{\theta}^\top \boldsymbol{\phi}_n \right) \quad (18)$$

where
$$\boldsymbol{\phi}_0 = (T, N)^{\top}$$
 and $\boldsymbol{\phi}_n = \left(1, \sum_{t_m \in \mathscr{H}_{t_n}} \operatorname{Exp}(t_n - t_m; \tau)\right)^{\top}$.

Questions: What approximation did we make? How would you maximize the log likelihood as a function of θ?

Marked point processes

► Now suppose we observed points from *S* difference **sources**.



- ▶ We can represent the points as a set of tuples, $\{(t_n, s_n)\}_{n=1}^N$ where $t_n \in [0, T]$ denotes the time and $s_n \in \{1, ..., S\}$ denotes the source of the *n*-th point.
- We will model them as a marked point process.
- Like before, we have a (conditional) intensity function, but this time is defined over time and marks,

$$\lambda(t, s \mid \mathscr{H}_t) : [0, T] \times \{1, \dots, S\} \mapsto \mathbb{R}_+$$



▶ When *s* takes on a discrete set of values, we often use the shorthand,

$$\lambda_{s}(t \mid \mathscr{H}_{t}) \triangleq \lambda(t, s \mid \mathscr{H}_{t})$$

to denote the intensity for the *s*-th source.

Multivariate Hawkes processes

A multivariate Hawkes process is a marked point process with mutually excitatory interactions.

It is defined by the conditional intensity functions,

$$\lambda_{s}(t \mid \mathscr{H}_{t}) = \lambda_{s,0} + \sum_{(t_{n},s_{n})\in\mathscr{H}_{t}} h_{s_{n},s}(t-t_{n}).$$
(21)

where $h_{s,s'}(\Delta t)$ is a **directed impulse response** from points on source *s* to the intensity of *s'*.

Again, it is common to model the impulse responses as weighted probability densities; e.g.,

$$h_{s,s'}(\Delta t) = w_{s,s'} \cdot \operatorname{Exp}(\Delta t; \tau_{s,s'})$$
(22)

where $w_{s,s'}$ is the weight.

Like before, the weights can be estimated using maximum likelihood estimation.

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(22)

where $w_{s,s'}$ is the weight.

Like before, the weights can be estimated using maximum likelihood estimation.

Multivariate Hawkes Processes II



Figure 1: Illustration of a Hawkes process. Events induce impulse responses on connected processes and spawn "child" events. See the main text for a complete description.

From Linderman and Adams [2014].

Discovering latent network structure in point process data

► We can think of the weights as defining a **directed network**,

$$\boldsymbol{W} = \begin{bmatrix} w_{1,1} & \dots & w_{1,S} \\ \vdots & & \vdots \\ w_{S,1} & \dots & w_{S,S} \end{bmatrix}$$

where $w_{s,s'} \in \mathbb{R}_+$ is the strength of influence that events (points) on source *s* induce on the intensity of source *s'*.

- However, we don't directly observe the network. We only observed it indirectly through the point process.
- Question: when is a multivariate Hawkes process stable, in that the intensity tends to a finite value in the infinite time limit?

(23)

Multivariate Hawkes processes as Poisson clustering processes

Note that the conditional intensity in eq. (21) is a sum of a background intensity and a bunch of non-negative impulse responses.

$$\lambda_{s}(t \mid \mathscr{H}_{t}) = \lambda_{0,s} + \sum_{(t_{n},s_{n})\in\mathscr{H}_{t}} h_{s_{n},s}(t-t_{n}).$$
(24)

• **Question:** which property of Poisson processes applied to such intensities?

Multivariate Hawkes processes as Poisson clustering processes

Note that the conditional intensity is a sum of a background intensity and a bunch of non-negative impulse responses,

$$\lambda_{s}(t \mid \mathcal{H}_{t}) = \lambda_{s,0} + \sum_{(t_{n},s_{n})\in\mathcal{H}_{t}} h_{s_{n},s}(t-t_{n}).$$
(25)

- Question: which property of Poisson processes applied to such intensities?
- ► Using the **Poisson superposition principle**, we can partition the points $\mathscr{T}_s = \{t_n : s_n = s\}$ from source *s* into **clusters** attributed to either the background or to one of the impulse responses.

$$\mathscr{T}_{s} = \bigcup_{n=0}^{N} \mathscr{T}_{s,n} \tag{26}$$

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where

$$\mathcal{T}_{s,0} \sim PP(\lambda_{s,0}) \qquad [background points] \qquad (27)$$

$$\mathcal{T}_{s,n} \sim PP(h_{s_n,s}(t-t_n)) \qquad [points induced by (t_n, s_n)] \qquad (28)$$

Multivariate Hawkes processes as Poisson clustering processes

Now the weights have an intuitive interpretation. Plugging in the definition of the impulse response,

$$\mathscr{T}_{s,n} \sim \operatorname{PP}\left(w_{s_n,s} \cdot \operatorname{Exp}(t - t_n; \tau_{s_n,s})\right).$$
 (29)

• Question: What is the expected number of points induced by this impulse response, i.e. $\mathbb{E}[|\mathscr{T}_{s,n}|]$?

Conjugate Bayesian inference for multivariate Hawkes processes

Let's put a gamma prior on the weights,

$$W_{s,s'} \sim \operatorname{Ga}(\alpha,\beta).$$
 (30)

• **Question:** suppose we know the partition of points; i.e. we knew the clusters $\mathcal{T}_{s,n}$. What is the conditional distribution,

$$p(w_{s,s'} | \{\{\mathcal{T}_{s,n}\}_{n=0}^N\}_{s=1}^S) =$$

(31)

Conjugate Bayesian inference for multivariate Hawkes processes II

- We don't know the partition of spikes in general, but we do know its conditional distribution!
- Let $z_n \in \{0, ..., n-1\}$ denote the cluster to which the *n*-th spike is assigned, with $z_n = 0$ denoting the background cluster. With this notation,

$$\mathscr{T}_{s,n} = \{ (t_{n'}, s_{n'}) : s_{n'} = s \land z_{n'} = n \}.$$
(32)

• **Question:** what is the conditional distribution of the cluster assignment, $p(z_n | \{(t_n, s_n)\}_{n=1}^N; \theta) =$

- (33)
- Using these two conditional distributions, we can derive a simple Gibbs sampling algorithm that alternates between sampling the weights given the clusters and the clusters given the weights.

Beyond Poisson: Doubly stochastic processes

- Hawkes processes are only one way of going beyond Poisson processes.
- Whereas Hawkes processes take an autoregressive approach, doubly stochastic point processes (a.k.a. Cox processes) take a latent variable approach.
- In these models, the intensity itself is modeled as a stochastic process,

 $\lambda(\mathbf{x}) \sim p(\lambda).$



For example, consider the model,

$$\lambda(\mathbf{x}) = g(f(\mathbf{x}))$$
 where $f \sim GP(\mu(\cdot), K(\cdot, \cdot))$. (35)

When *g* is the exponential function, this is called a **log Gaussian Cox process**. When *g* is the sigmoid function, this is called a **sigmoidal Gaussian Cox process** [Adams et al., 2009].

Aternatively, take λ to be a convolution of a Poisson process with a non-negative kernel; this is called a Neyman-Scott process [Wang et al., 2022, e.g.].

$$f \sim GP(\mu, K)$$

$$\lambda(x) = \lambda_{mex} \equiv (f(x))$$

$$\int X_n \int_{n=1}^{N} \sim PP(\lambda(x))$$

$$\Rightarrow \int r_m \int_{m=1}^{N} \sim PP(\lambda_{max})$$

$$\Rightarrow y_m \sim Bern(\frac{\lambda(r_m)}{\lambda_{max}})$$

$$= Bern(\equiv (f(r_m)))$$

$$\Rightarrow Set \{X_n\}_{n=1}^{N} = \{r_m : y_m = 1\}$$





Conclusion

- Poisson processes are stochastic processes that generate discrete sets of points.
- They are defined by an intensity function $\lambda(\mathbf{x})$, which specifies the expected number of points in each interval of time or space.
- We can build in dependencies by conditioning on past points or introducing latent variables.
- Poisson process modeling boils down to inferring the intensity. We can take various parametric and nonparametric approaches.
- ► The hardness comes about when the integral in the Poisson process likelihood is intractable.
- As we will see next time, Poisson processes are also mathematical building blocks for Bayesian nonparametric models with random measures.

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